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Dempster Shafer perhitungan part 3A survey on Dempster-Shafer Theory in geographic information systems *Dempster Shafer Theory part - 2 Advances In The Dempster Shafer*

Jaffray- 1994- In R. Yager, M. Fedrizzi & J. Kacprzyk (eds.), Advances in the Dempster- Shafer Theory of Evidence. John Wiley. pp. 331-352. Connecting Dempster-Shafer Belief Functions with Likelihood-Based Inference. Mikel Aickin- 2000- Synthese123 (3):347-364.

Advances in the Dempster- Shafer Theory of Evidence

Salmane H, Ruichek Y and Khoudour L Using hidden markov model and dempster-shafer theory for evaluating and detecting dangerous situations in level crossing environments Proceedings of the 11th Mexican international conference on Advances in Artificial Intelligence - Volume Part I, (131-145)

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Advances in the Dempster-Shafer theory of evidence

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Advances In The Dempster Shafer Theory Of Evidence [PDF]

Dempster-Shafer belief structures provide a useful framework for the representation of information about a variable whose value is uncertain. Important parameters in these structures are the weights associated with the focal elements. These weights, which can be viewed as probabilities, are required to be precisely known.

Dempster-Shafer belief structures with interval valued

The latest developments in Markov models' theory and their corresponding computational techniques have opened new rooms for image and signal modeling. In particular, the use of Dempster-Shafer theory of evidence within Markov models has brought some keys to several challenging difficulties that the conventional hidden Markov models cannot handle.

Dempster-Shafer fusion of multisensor signals in

In Dempster-Shafer combination rule, k is a coefficient to measure the conflict between evidence. If k=1, we cannot fusion information by Dempster combination rule. When k ! 1, there is a result that contrary to 2 Advances in Mechanical Engineering

Advances in Mechanical Engineering 2016, Vol. 8(3) 1-7 An

The Dempster's rule of combination is one of the decision fusion methods used frequently in many research areas. However, there are so many uncertainties in classifier output. Hence, we propose a fuzzy Dempster's rule of combination (FDST) where we fuzzify the discounted basic probability assignment and compute the fuzzy combination.

Decision Fusion Using Fuzzy Dempster-Shafer Theory

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Advances in the Dempster-Shafer theory of evidence (Book

Advances in the Dempster-Shafer Theory of Evidence. Builds on classical probability theory and offers an extremely workable solution to the many problems of artificial intelligence, concentrating on the rapidly growing areas of fuzzy reasoning and neural computing.

Advances in the Dempster-Shafer Theory of Evidence : R. R

Baldwin, JF 1994, Mass assignments and fuzzy sets for fuzzy databases. in RR Yager, M Fedrizzi & J Kacprzyk (eds), Advances in the Dempster-Shafer theory of evidence. John Wiley & Sons, Inc, pp. 577 - 594.

Mass assignments and fuzzy sets for fuzzy databases

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Builds on classical probability theory and offers an extremely workable solution to the many problems of artificial intelligence, concentrating on the rapidly growing areas of fuzzy reasoning and neural computing. Contains a collection of previously unpublished articles by leading researchers in the field.

Both in science and in practical affairs we reason by combining facts only inconclusively supported by evidence. Building on an abstract understanding of this process of combination, this book constructs a new theory of epistemic probability. The theory draws on the work of A. P. Dempster but diverges from Depster's viewpoint by identifying his "lower probabilities" as epistemic probabilities and taking his rule for combining "upper and lower probabilities" as fundamental. The book opens with a critique of the well-known Bayesian theory of epistemic probability. It then proceeds to develop an alternative to the additive set functions and the rule of conditioning of the Bayesian theory: set functions that need only be what Choquet called "monotone of order of infinity." and Dempster's rule for combining such set functions. This rule, together with the idea of "weights of evidence," leads to both an extensive new theory and a better understanding of the Bayesian theory. The book concludes with a brief treatment of statistical inference and a discussion of the limitations of epistemic probability. Appendices contain mathematical proofs, which are relatively elementary and seldom depend on mathematics more advanced than the binomial theorem.

The theory of belief functions, also known as evidence theory or Dempster-Shafer theory, was first introduced by Arthur P. Dempster in the context of statistical inference, and was later developed by Glenn Shafer as a general framework for modeling epistemic uncertainty. These early contributions have been the starting points of many important developments, including the Transferable Belief Model and the Theory of Hints. The theory of belief functions is now well established as a general framework for reasoning with uncertainty, and has well understood connections to other frameworks such as probability, possibility and imprecise probability theories. This volume contains the proceedings of the 2nd International Conference on Belief Functions that was held in Compiègne, France on 9-11 May 2012. It gathers 51 contributions describing recent developments both on theoretical issues (including approximation methods, combination rules, continuous belief functions, graphical models and independence concepts) and applications in various areas including classification, image processing, statistics and intelligent vehicles.

This is a collection of classic research papers on the Dempster-Shafer theory of belief functions. The book is the authoritative reference in the field of evidential reasoning and an important archival reference in a wide range of areas including uncertainty reasoning in artificial intelligence and decision making in economics, engineering, and management. The book includes a foreword reflecting the development of the theory in the last forty years.

This second volume dedicated to Dezert-Smarandache Theory (DSmT) in Information Fusion brings in new fusion quantitative rules (such as the PCR1-6, where PCR5 for two sources does the most mathematically exact redistribution of conflicting masses to the non-empty sets in the fusion literature), qualitative fusion rules, and the Belief Conditioning Rule (BCR) which is different from the classical conditioning rule used by the fusion community working with the Mathematical Theory of Evidence. Other fusion rules are constructed based on T-norm and T-conorm (hence using fuzzy logic and fuzzy set in information fusion), or more general fusion rules based on N-norm and N-conorm (hence using neutrosophic logic and neutrosophic set in information fusion), and an attempt to unify the fusion rules and fusion theories. The known fusion rules are extended from the power set to the hyper-power set and comparison between rules are made on many examples. One defines the degree of intersection of two sets, degree of union of two sets, and degree of inclusion of two sets which all help in improving the all existing fusion rules as well as the credibility, plausibility, and communality functions. The book chapters are written by Frederic Dambreville, Milan Daniel, Jean Dezert, Pascal Djiknavorian, Dominic Grenier, Xinhua Huang, Pavlina Dimitrova Konstantinova, Xinde Li, Arnaud Martin, Christophe Osswald, Andrew Schumann, Tzvetan Atanasov Semerdjiev, Florentin Smarandache, Albena Tchamova, and Min Wang.

The Handbook of Defeasible Reasoning and Uncertainty Management Systems is unique in its masterly survey of the computational and algorithmic problems of systems of applied reasoning. The various theoretical and modelling aspects of defeasible reasoning were dealt with in the first four volumes, and Volume 5 now turns to the algorithmic aspect. Topics covered include: Computation in valuation algebras; consequence finding algorithms; possibilistic logic; probabilistic argumentation systems, networks and satisfiability; algorithms for imprecise probabilities, for Dempster-Shafer, and network based decisions.

Remote sensing is the acquisition of information of an object or phenomenon, by the use of either recording or real-time sensing device(s), that is not in physical or intimate contact with the object (such as by way of aircraft, spacecraft, satellite, buoy, or ship). In practice, remote sensing is the stand-off collection through the use of a variety of devices for gathering information on a given object or area. Human existence is dependent on our ability to understand, utilize, manage and maintain the environment we live in - Geoscience is the science that seeks to achieve these goals. This book is a collection of contributions from world-class scientists, engineers and educators engaged in the fields of geoscience and remote sensing.

This volume presents the state of the art of new developments, and some interesting and relevant applications of the OWA (ordered weighted averaging) operators. The OWA operators were introduced in the early 1980s by Ronald R. Yager as a conceptually and numerically simple, easily implementable, yet extremely powerful general aggregation operator. That simplicity, generality and implementability of the OWA operators, combined with their intuitive appeal, have triggered much research both in the foundations and extensions of the OWA operators, and in their applications to a wide variety of problems in various fields of science and technology. Part I: Methods includes papers on theoretical foundations of OWA operators and their extensions. The papers in Part II: Applications show some more relevant applications of the OWA operators, mostly means, as powerful yet general aggregation operators. The application areas are exemplified by environmental modeling, social networks, image analysis, financial decision making and water resource management.

This book constitutes the refereed proceedings of the 10th International Symposium on Methodologies for Intelligent Systems, ISMIS'97, held in Charlotte, NC, USA, in October 1997. The 57 revised full papers were selected from a total of 117 submissions. Also included are four invited papers. Among the topics covered are intelligent information systems, approximate reasoning, evolutionary computation, knowledge representation and integration, learning and knowledge discovery, AI-Logics, discovery systems, data mining, query processing, etc.

In this short paper, we present an introduction of our recent theory of plausible and paradoxical reasoning, known as Dezert-Smarandache Theory (DSmT), developed for dealing with imprecise, uncertain and conflicting sources of information. We focus our presentation on the foundations of DSmT and on its most important rules of combination, rather than on browsing specific applications of DSmT available in literature. Several simple examples are given throughout this presentation to show the efficiency and the generality of this new theory.

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