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Solution: Writing down the kinetic and potential energy yields: $T = \frac{1}{2} m \dot{\theta}^2$, $U = \frac{1}{2} kx^2 + mgh$. $U = \frac{1}{2} kl^2 \sin^2 \theta + mgl(1 - \cos \theta)$ Here the spring deflects a distance $l \sin \theta$, and the mass drops a distance $l(1 - \cos \theta)$. Adding up the total energy and taking its time derivative yields: $\frac{d}{dt} T + U = 0$

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Solution: From Window 1.1, the linear equation of the pendulum is. For zero initial position, the solution is given in equation (1.10) by. since sin is always less then one. Thus if we need $\theta < 10^\circ = 0.175 \text{ rad}$, then we need to. solve: for $v > 0$ which yields: $v > 0 < 0.773 \text{ rad/s}$. $(\theta + t) = 0$. $g \cdot t \cdot \sin(\theta) = v \cdot 0! \cdot g \cdot \sin(g \cdot t) \cdot \sin(\theta) \cdot v \cdot 0! \cdot g \cdot 0.175 \cdot 81.05 = v$

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Serving as both a text and reference manual, Engineering Vibration, 4e, connects traditional design-oriented topics, the introduction of modal analysis, and the use of MATLAB, Mathcad, or Mathematica. The author provides an unequalled combination of the study of conventional vibration with the use of vibration design, computation, analysis and testing in various engineering applications.

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